

VETTORI GEOMETRICI (FORZE TRIDIMENSIONALI)

Somma di due vettori; la seguente procedura "disegna" la somma di due vettori definiti dal loro secondo estremo; rispettivamente P e Q.

```
> with(plots):
> somma:=proc(P,Q)
  local OO,u,v,upiuu,uu,vv,M;
  OO:=[0,0,0];
  u:=[OO,P];
  uu:=[Q,P+Q];
  v:=[P,P+Q];
  vv:=[OO,Q];
  upiuu:=[OO,P+Q];
  M:=PLOT3D(CURVES(u,v,COLOR(RED,0,1,0)),CURVES(upiuu,COLOR(RED,1,0,0)),
  CURVES(uu,vv,COLOR(RED,0,0,0)),AXESSTYLE(FRAME),AXESLABELS("x",
  "y","z"),POINTS(P,P+Q,Q,SYMBOL(BOX),COLOR(RED,0,0,1)),TEXT(P-[1,1,1],
  "u"),TEXT(P+[0,1,2],"v"),TEXT((P+Q)-[2,2,1.5],"u+v"),COLOR(ZHUE)
  E)):
  display3d([M],orientation=[-52,49]);
end;
```

somma := proc(P, Q)

local *OO, u, v, upiuu, uu, vv, M;*

OO := [0, 0, 0];

u := [OO, P];

uu := [Q, P + Q];

v := [P, P + Q];

vv := [OO, Q];

upiuu := [OO, P + Q];

M := PLOT3D(CURVES(u, v, COLOR(RED, 0, 1, 0)),

CURVES(upiuu, COLOR(RED, 1, 0, 0)), CURVES(uu, vv, COLOR(RED, 0, 0, 0)),

AXESSTYLE(FRAME), AXESLABELS("x", "y", "z"),

POINTS(P, P + Q, Q, SYMBOL(BOX), COLOR(RED, 0, 0, 1)),

TEXT(P + [-1, -1, -1], "u"), TEXT(P + [0, 1, 2], "v"),

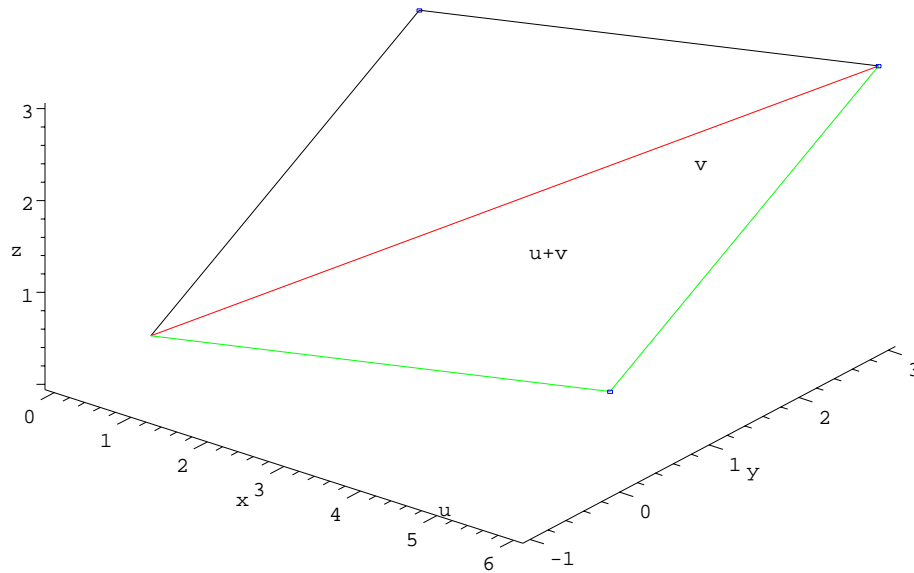
TEXT(P + Q + [-2, -2, -1.5], "u+v"), COLOR(ZHUE));

display3d([M], orientation = [-52, 49])

end

Esempio: $u=[6,0,4]$, $v=[0,5,5]$ sono in verde; $u+v=[6,5,9]$ in rosso.

```
> somma([6,0,1],[0,3,2]);
```



Proprieta' associativa della somma. Verifica grafica.

```
> prop_ass:=proc(P,Q,R)
  local OO,u,v,w,upiuw,upiuvpuiw,vpiuw,M;
  OO:=[0,0,0];
  u:=[OO,P];
  v:=[P,P+Q];
  w:=[P+Q,P+Q+R];
  upiuw:=[OO,P+Q];
  upiuvpuiw:=[OO,P+Q+R];
  vpiuw:=[P,P+Q+R];
  M:=PLOT3D(CURVES(u,v,w,COLOR(RED,0,1,0)),CURVES(upiuw,vpiuw,COLOR(
  RED,0,0,1)),CURVES(upiuvpuiw,COLOR(RED,1,0,0)),AXESSTYLE(FRAME),AX
  ESLABELS("x","y","z"),POINTS(P,P+Q,P+Q+R,SYMBOL(BOX),COLOR(RED,0,0
  ,0)),TEXT(P-[1,1,1],"u"),TEXT(P+[0,1,2],"v"),TEXT((P+Q)+[1,1,1],"w
  "),TEXT((P+Q)-[2,2,1.5],"u+v"),TEXT((P+Q+R)-[0,5,1.5],"v+w"),TEXT(
  P-[1,1,1],"u"),COLOR(ZHUE));
  display3d([M],orientation=[-52,49]);
end;
```

```
prop_ass := proc(P, Q, R)
```

```
local OO, u, v, w, upiuw, upiuvpuiw, vpiuw, M;
```

```
OO := [0, 0, 0];
```

```

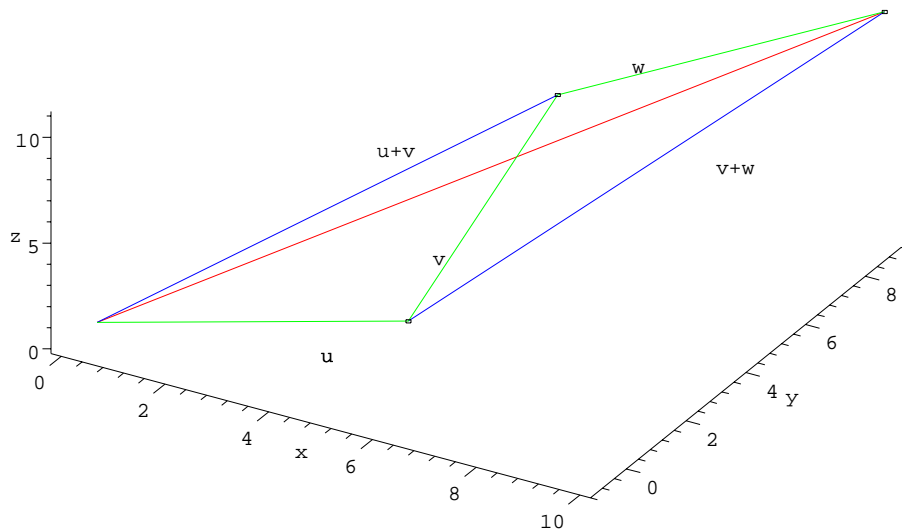
u := [OO, P];
v := [P, P + Q];
w := [P + Q, P + Q + R];
upiuw := [OO, P + Q];
upiuwpiuw := [OO, P + Q + R];
vpuiw := [P, P + Q + R];
M := PLOT3D(CURVES(u, v, w, COLOR(RGB, 0, 1, 0)),
  CURVES(upiuw, vpuiw, COLOR(RGB, 0, 0, 1)),
  CURVES(upiuwpiuw, COLOR(RGB, 1, 0, 0)), AXESSTYLE(FRAME),
  AXESLABELS("x", "y", "z"),
  POINTS(P, P + Q, P + Q + R, SYMBOL(BOX), COLOR(RGB, 0, 0, 0)),
  TEXT(P + [-1, -1, -1], "u"), TEXT(P + [0, 1, 2], "v"), TEXT(P + Q + [1, 1, 1], "w"),
  TEXT(P + Q + [-2, -2, -1.5], "u+v"), TEXT(P + Q + R + [0, -5, -1.5], "v+w"),
  TEXT(P + [-1, -1, -1], "u", COLOR(ZHUE)));
display3d([M], orientation = [-52, 49])

```

end

Esempio: Ai due vettori di prima aggiungiamo il vettore $w=[4,4,2]$;

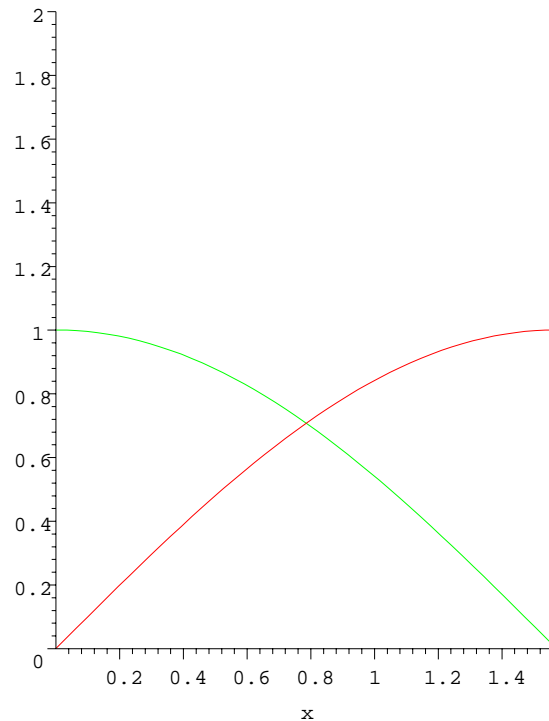
```
> prop_ass([6, 0, 4], [0, 5, 5], [4, 4, 2]);
```



SPAZIO VETTORIALE DELLE FUNZIONI DEFINITE SU UN INTERVALLO

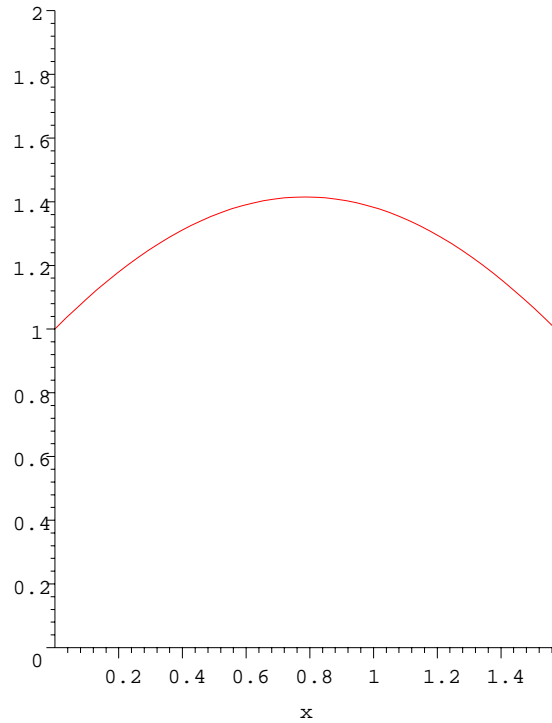
Prendiamo $\sin(x)$ (grafico rosso) e $\cos(x)$ (grafico verde) definite sull'intervallo $[0, \pi/2]$.

```
> plot([sin(x),cos(x)],x=0..Pi/2,0..2,scaling=CONSTRAINED);
```



Sommiamo $\sin+\cos$; otteniamo la funzione seguente:

```
> plot(sin(x)+cos(x),x=0..Pi/2,0..2,scaling=CONSTRAINED);
```



Verifica "sperimentale" della proprietà associativa. Prendiamo $h(x)=x$; calcoliamo $(\sin+\cos)+h$:

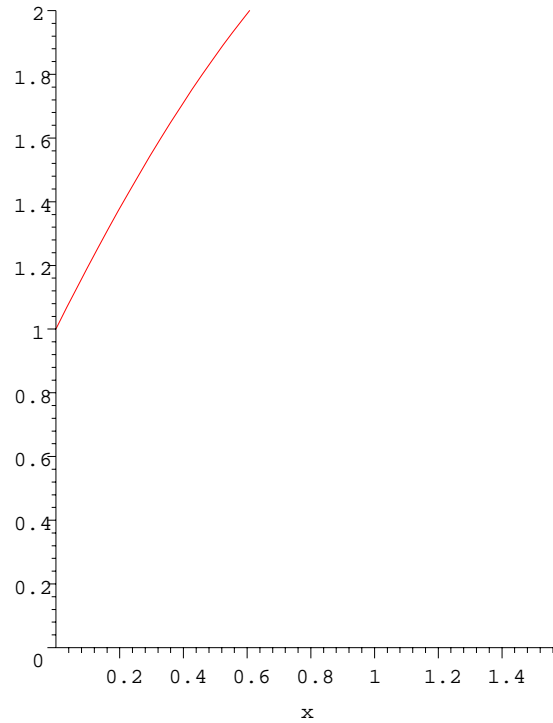
```
> h(x) := x;
```

```
h(x) := x
```

```
> f(x) := sin(x) + cos(x);
```

```
f(x) := sin(x) + cos(x)
```

```
> plot(f(x)+h(x), x=0..Pi/2, 0..2, scaling=CONSTRAINED);
```

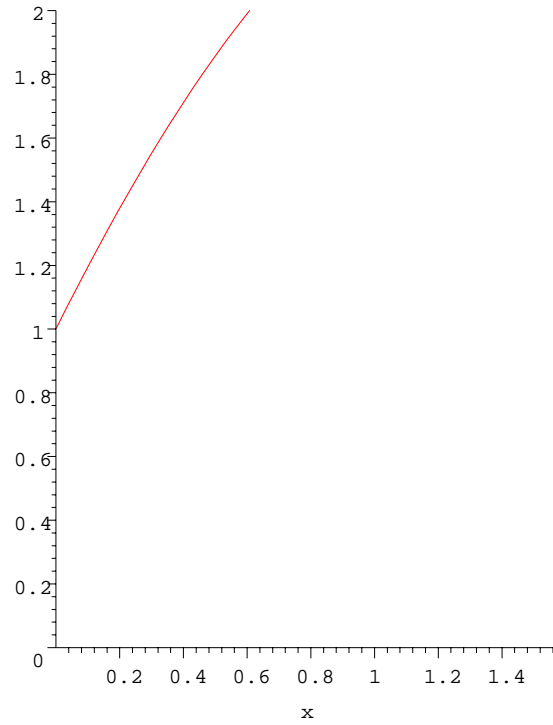


Calcoliamo ora $\sin+(\cos+h)$;

```
> g(x) := cos(x) + h(x) ;
```

```
g(x) := cos(x) + x
```

```
> plot(sin(x)+g(x), x=0..Pi/2, 0..2, scaling=CONSTRAINED) ;
```

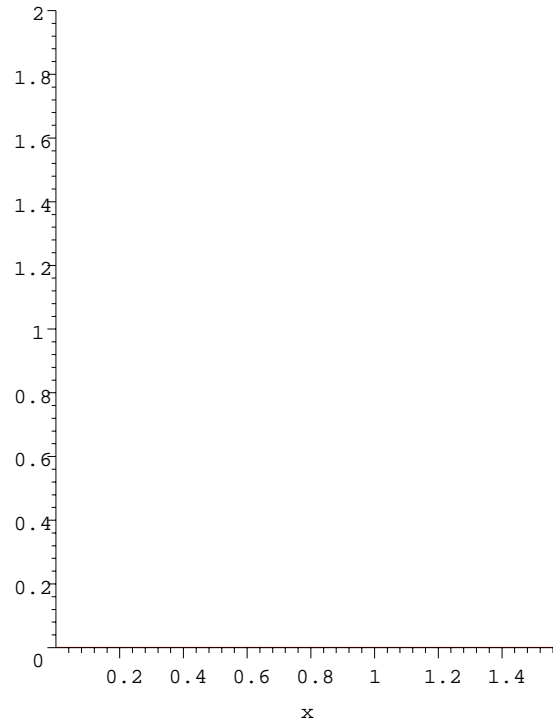


Funzione nulla: $OO(x) := 0$;

```
> OO(x) := 0;
```

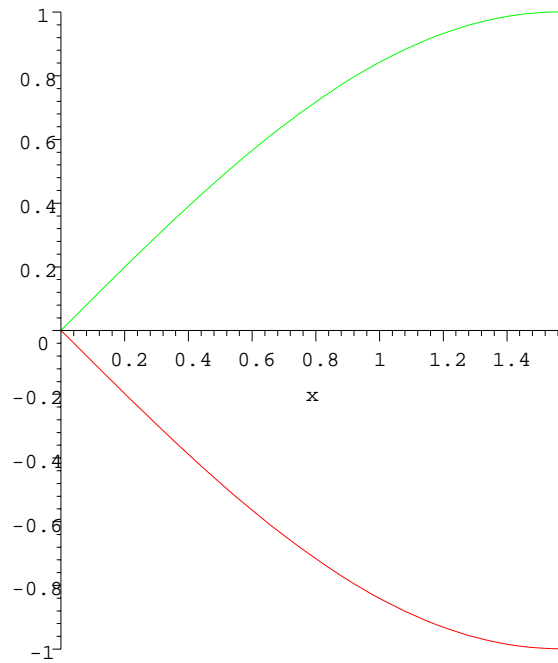
$OO(x) := 0$

```
> plot(OO(x), x=0..Pi/2, 0..2, scaling=CONSTRAINED);
```



Funzione opposta. Se $f(x) := \sin(x)$, allora:

```
> plot([-sin(x), sin(x)], x=0..Pi/2, -1..1, scaling=CONSTRAINED);
```



SPAZIO VETTORIALE DELLE MATRICI

Manipolazione simbolica delle matrici. Caso di matrici 3x4; esempio:

```
> with(linalg):
```

```
> A:=matrix([[a[1,1],a[1,2],a[1,3],a[1,4]], [a[2,1],a[2,2],a[2,3],a[2,4]], [a[3,1],a[3,2],a[3,3],a[3,4]]]);
```

$$A := \begin{bmatrix} a_{1,1} & a_{1,2} & a_{1,3} & a_{1,4} \\ a_{2,1} & a_{2,2} & a_{2,3} & a_{2,4} \\ a_{3,1} & a_{3,2} & a_{3,3} & a_{3,4} \end{bmatrix}$$

```
> B:=matrix([[b[1,1],b[1,2],b[1,3],b[1,4]], [b[2,1],b[2,2],b[2,3],b[2,4]], [b[3,1],b[3,2],b[3,3],b[3,4]]]);
```

$$B := \begin{bmatrix} b_{1,1} & b_{1,2} & b_{1,3} & b_{1,4} \\ b_{2,1} & b_{2,2} & b_{2,3} & b_{2,4} \\ b_{3,1} & b_{3,2} & b_{3,3} & b_{3,4} \end{bmatrix}$$

```
> C:=matrix([[c[1,1],c[1,2],c[1,3],c[1,4]], [c[2,1],c[2,2],c[2,3],c[2,4]], [c[3,1],c[3,2],c[3,3],c[3,4]]]);
```

$$C := \begin{bmatrix} c_{1,1} & c_{1,2} & c_{1,3} & c_{1,4} \\ c_{2,1} & c_{2,2} & c_{2,3} & c_{2,4} \\ c_{3,1} & c_{3,2} & c_{3,3} & c_{3,4} \end{bmatrix}$$

```
> H:=matadd(A,B);
```

$$H := \begin{bmatrix} a_{1,1} + b_{1,1} & a_{1,2} + b_{1,2} & a_{1,3} + b_{1,3} & a_{1,4} + b_{1,4} \\ a_{2,1} + b_{2,1} & a_{2,2} + b_{2,2} & a_{2,3} + b_{2,3} & a_{2,4} + b_{2,4} \\ a_{3,1} + b_{3,1} & a_{3,2} + b_{3,2} & a_{3,3} + b_{3,3} & a_{3,4} + b_{3,4} \end{bmatrix}$$

(A+B)+C:

```
> DD:=matadd(H,C);
```

$$DD := \begin{bmatrix} a_{1,1} + b_{1,1} + c_{1,1} & a_{1,2} + b_{1,2} + c_{1,2} & a_{1,3} + b_{1,3} + c_{1,3} & a_{1,4} + b_{1,4} + c_{1,4} \\ a_{2,1} + b_{2,1} + c_{2,1} & a_{2,2} + b_{2,2} + c_{2,2} & a_{2,3} + b_{2,3} + c_{2,3} & a_{2,4} + b_{2,4} + c_{2,4} \\ a_{3,1} + b_{3,1} + c_{3,1} & a_{3,2} + b_{3,2} + c_{3,2} & a_{3,3} + b_{3,3} + c_{3,3} & a_{3,4} + b_{3,4} + c_{3,4} \end{bmatrix}$$

```
> K:=matadd(B,C);
```

$$K := \begin{bmatrix} b_{1,1} + c_{1,1} & b_{1,2} + c_{1,2} & b_{1,3} + c_{1,3} & b_{1,4} + c_{1,4} \\ b_{2,1} + c_{2,1} & b_{2,2} + c_{2,2} & b_{2,3} + c_{2,3} & b_{2,4} + c_{2,4} \\ b_{3,1} + c_{3,1} & b_{3,2} + c_{3,2} & b_{3,3} + c_{3,3} & b_{3,4} + c_{3,4} \end{bmatrix}$$

A+(B+C):

```
> matadd(A,K);
```

$$\begin{bmatrix} a_{1,1} + b_{1,1} + c_{1,1} & a_{1,2} + b_{1,2} + c_{1,2} & a_{1,3} + b_{1,3} + c_{1,3} & a_{1,4} + b_{1,4} + c_{1,4} \\ a_{2,1} + b_{2,1} + c_{2,1} & a_{2,2} + b_{2,2} + c_{2,2} & a_{2,3} + b_{2,3} + c_{2,3} & a_{2,4} + b_{2,4} + c_{2,4} \\ a_{3,1} + b_{3,1} + c_{3,1} & a_{3,2} + b_{3,2} + c_{3,2} & a_{3,3} + b_{3,3} + c_{3,3} & a_{3,4} + b_{3,4} + c_{3,4} \end{bmatrix}$$

Prodotto per uno scalare:

```
> scalarmul(A,c);
```

$$\begin{bmatrix} c a_{1,1} & c a_{1,2} & c a_{1,3} & c a_{1,4} \\ c a_{2,1} & c a_{2,2} & c a_{2,3} & c a_{2,4} \\ c a_{3,1} & c a_{3,2} & c a_{3,3} & c a_{3,4} \end{bmatrix}$$

Manipolazione numerica; caso delle matrici 4x5:

```
> A:=matrix([[1,2,3,2,4],[0,3,4,5,2],[2,1,1,0,2],[0,0,3,4,1]]);
```

$$A := \begin{bmatrix} 1 & 2 & 3 & 2 & 4 \\ 0 & 3 & 4 & 5 & 2 \\ 2 & 1 & 1 & 0 & 2 \\ 0 & 0 & 3 & 4 & 1 \end{bmatrix}$$

```
> B:=matrix([[1,2,1,2,2],[0,2,0,0,4],[2,1,1,1,3],[1,1,3,1,2]]);
```

$$B := \begin{bmatrix} 1 & 2 & 1 & 2 & 2 \\ 0 & 2 & 0 & 0 & 4 \\ 2 & 1 & 1 & 1 & 3 \\ 1 & 1 & 3 & 1 & 2 \end{bmatrix}$$

```
> matadd(A,B);
```

$$\begin{bmatrix} 2 & 4 & 4 & 4 & 6 \\ 0 & 5 & 4 & 5 & 6 \\ 4 & 2 & 2 & 1 & 5 \\ 1 & 1 & 6 & 5 & 3 \end{bmatrix}$$

```
> scalarmul(A,4);
```

$$\begin{bmatrix} 4 & 8 & 12 & 8 & 16 \\ 0 & 12 & 16 & 20 & 8 \\ 8 & 4 & 4 & 0 & 8 \\ 0 & 0 & 12 & 16 & 4 \end{bmatrix}$$

SPAZIO VETTORIALE \mathbb{R}^n

Somma di n-uple:

```

[ > u:=[a,b,c,d,e];
[                                     u := [a, b, c, d, e]
[ > v:=[m,n,p,q,r];
[                                     v := [m, n, p, q, r]
[ > u+v;
[                                     [m + a, n + b, p + c, q + d, r + e]

```

Prodotto per uno scalare:

```

[ > expand(h*u);
[                                     [a h, b h, c h, d h, e h]

```

Effetto di h*u:

```

[ > h*u;
[                                     h [a, b, c, d, e]

```

SPAZIO VETTORIALE DEI POLINOMI $\mathbb{R}[x]$

I polinomi (ad una indeterminata sul campo reale) sono scritte del tipo:

```

[ > f:=2*x^4+3*x^3+4*x+5;
[                                     f := 2 x4 + 3 x3 + 4 x + 5

```

L'insieme dei polinomi a coefficienti reali si denota con $\mathbb{R}[x]$. Due polinomi si possono sommare:

```

[ > g:=-2*x^4+x^3+x^2+4*x;
[                                     g := -2 x4 + x3 + x2 + 4 x
[ > f+g;
[                                     4 x3 + 8 x + 5 + x2

```

Si puo' moltiplicare un polinomio per un numero:

```

[ > 3*f;
[                                     6 x4 + 9 x3 + 12 x + 15
[ >

```