

# Inverse problems with unknown boundaries: uniqueness and stability

Giovanni Alessandrini<sup>1</sup>

<sup>1</sup>  Università di Trieste

Cartagena, PICO F 2010

Introduction

Insulating  
cavity in a  
conductor.

Strategy for  
uniqueness.

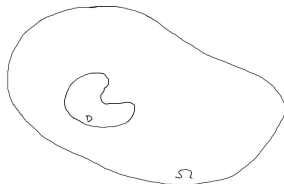
Tools for stability.

Cavity with  
boundary  
impedance.

Rigid inclusion  
in an elastic  
body.

End.

# A family of problems



Consider a body  $\Omega \subset \mathbb{R}^n$  which might contain an unknown, inaccessible, cavity  $D$  (or an inclusion). To detect the presence and the shape of  $D$  from measurements taken from the exterior, accessible, boundary of  $\Omega$ , when some field (electric, electromagnetic, thermal, elastic, ...) is applied to it.

Introduction

Insulating  
cavity in a  
conductor.

Strategy for  
uniqueness.

Tools for stability.

Cavity with  
boundary  
impedance.

Rigid inclusion  
in an elastic  
body.

End.

# A family of problems

- $\Omega$  electrical conductor,  $D$  cavity with insulating boundary,
- $\Omega$  electrical conductor,  $D$  perfectly conducting inclusion,

Andrieux, Ben Abda, Jaoua (1993), Beretta, Vessella (1996), Bukhgeim, Cheng, Yamamoto (1998, 1999, 2000) Cheng, Hon and Yamamoto (2001), A., Beretta, Rosset, Vessella (2000), A., Rondi (2001).

- $\Omega$  electrical conductor,  $D$  cavity with boundary impedance,

Cakoni, Kress (2007), Rundell (2008), Bacchelli (2009), Pagani, Pierotti (2009), Sincich (2010).

# A family of problems

- $\Omega$  electrical conductor,  $D$  cavity with insulating boundary,
- $\Omega$  electrical conductor,  $D$  perfectly conducting inclusion,

Andrieux, Ben Abda, Jaoua (1993), Beretta, Vessella (1996), Bukhgeim, Cheng, Yamamoto (1998, 1999, 2000) Cheng, Hon and Yamamoto (2001), A., Beretta, Rosset, Vessella (2000), A., Rondi (2001).

- $\Omega$  electrical conductor,  $D$  cavity with boundary impedance,

Cakoni, Kress (2007), Rundell (2008), Bacchelli (2009), Pagani, Pierotti (2009), Sincich (2010).

Introduction

Insulating  
cavity in a  
conductor.

Strategy for  
uniqueness.

Tools for stability.

Cavity with  
boundary  
impedance.

Rigid inclusion  
in an elastic  
body.

End.

# A family of problems

- $\Omega$  electrical conductor,  $D$  cavity with insulating boundary,
- $\Omega$  electrical conductor,  $D$  perfectly conducting inclusion,

Andrieux, Ben Abda, Jaoua (1993), Beretta, Vessella (1996), Bukhgeim, Cheng, Yamamoto (1998, 1999, 2000) Cheng, Hon and Yamamoto (2001), A., Beretta, Rosset, Vessella (2000), A., Rondi (2001).

- $\Omega$  electrical conductor,  $D$  cavity with boundary impedance,

Cakoni, Kress (2007), Rundell (2008), Bacchelli (2009), Pagani, Pierotti (2009), Sincich (2010).

Introduction

Insulating  
cavity in a  
conductor.

Strategy for  
uniqueness.

Tools for stability.

Cavity with  
boundary  
impedance.

Rigid inclusion  
in an elastic  
body.

End.

# A family of problems

- $\Omega$  electrical conductor,  $D$  cavity with insulating boundary,
- $\Omega$  electrical conductor,  $D$  perfectly conducting inclusion,

Andrieux, Ben Abda, Jaoua (1993), Beretta, Vessella (1996), Bukhgeim, Cheng, Yamamoto (1998, 1999, 2000) Cheng, Hon and Yamamoto (2001), A., Beretta, Rosset, Vessella (2000), A., Rondi (2001).

- $\Omega$  electrical conductor,  $D$  cavity with boundary impedance,

Cakoni, Kress (2007), Rundell (2008), Bacchelli (2009), Pagani, Pierotti (2009), Sincich (2010).

Introduction

Insulating  
cavity in a  
conductor.

Strategy for  
uniqueness.

Tools for stability.

Cavity with  
boundary  
impedance.

Rigid inclusion  
in an elastic  
body.

End.

# A family of problems

- $\Omega$  electrical conductor,  $D$  cavity with insulating boundary,
- $\Omega$  electrical conductor,  $D$  perfectly conducting inclusion,

Andrieux, Ben Abda, Jaoua (1993), Beretta, Vessella (1996), Bukhgeim, Cheng, Yamamoto (1998, 1999, 2000) Cheng, Hon and Yamamoto (2001), A., Beretta, Rosset, Vessella (2000), A., Rondi (2001).

- $\Omega$  electrical conductor,  $D$  cavity with boundary impedance,

Cakoni, Kress (2007), Rundell (2008), Bacchelli (2009), Pagani, Pierotti (2009), Sincich (2010).

# A family of problems

## Introduction

Insulating  
cavity in a  
conductor.

Strategy for  
uniqueness.

Tools for stability.

Cavity with  
boundary  
impedance.

Rigid inclusion  
in an elastic  
body.

End.

- $\Omega$  electrical conductor,  $D$  cavity with insulating boundary,
- $\Omega$  electrical conductor,  $D$  perfectly conducting inclusion,

Andrieux, Ben Abda, Jaoua (1993), Beretta, Vessella (1996), Bukhgeim, Cheng, Yamamoto (1998, 1999, 2000) Cheng, Hon and Yamamoto (2001), A., Beretta, Rosset, Vessella (2000), A., Rondi (2001).

- $\Omega$  electrical conductor,  $D$  cavity with boundary impedance,

Cakoni, Kress (2007), Rundell (2008), Bacchelli (2009), Pagani, Pierotti (2009), Sincich (2010).



# A family of problems

## Introduction

Insulating  
cavity in a  
conductor.

Strategy for  
uniqueness.

Tools for stability.

Cavity with  
boundary  
impedance.

Rigid inclusion  
in an elastic  
body.

End.

- $\Omega$  elastic body,  $D$  cavity,

Higashimori (2002), Morassi, Rosset (2004).

- $\Omega$  elastic body,  $D$  rigid inclusion,

Morassi, Rosset (2009).

- $\Omega$  fluid container,  $D$  immersed body,

Alvarez, Conca, Friz, Kavian, Ortega (2005), Doubova,  
Fernández-Cara, González-Burgos, Ortega (2006),  
Doubova, Fernández-Cara, Ortega (2007), Ballerini (2010).

# A family of problems

## Introduction

Insulating  
cavity in a  
conductor.

Strategy for  
uniqueness.

Tools for stability.

Cavity with  
boundary  
impedance.

Rigid inclusion  
in an elastic  
body.

End.

- $\Omega$  elastic body,  $D$  cavity,

Higashimori (2002), Morassi, Rosset (2004).

- $\Omega$  elastic body,  $D$  rigid inclusion,

Morassi, Rosset (2009).

- $\Omega$  fluid container,  $D$  immersed body,

Alvarez, Conca, Friz, Kavian, Ortega (2005), Doubova,  
Fernández-Cara, González-Burgos, Ortega (2006),  
Doubova, Fernández-Cara, Ortega (2007), Ballerini (2010).

# A family of problems

## Introduction

Insulating  
cavity in a  
conductor.

Strategy for  
uniqueness.

Tools for stability.

Cavity with  
boundary  
impedance.

Rigid inclusion  
in an elastic  
body.

End.

- $\Omega$  elastic body,  $D$  cavity,

Higashimori (2002), Morassi, Rosset (2004).

- $\Omega$  elastic body,  $D$  rigid inclusion,

Morassi, Rosset (2009).

- $\Omega$  fluid container,  $D$  immersed body,

Alvarez, Conca, Friz, Kavian, Ortega (2005), Doubova,  
Fernández-Cara, González-Burgos, Ortega (2006),  
Doubova, Fernández-Cara, Ortega (2007), Ballerini (2010).

Introduction

Insulating  
cavity in a  
conductor.

Strategy for  
uniqueness.

Tools for stability.

Cavity with  
boundary  
impedance.

Rigid inclusion  
in an elastic  
body.

End.

# A family of problems

- $\Omega$  elastic body,  $D$  cavity,

Higashimori (2002), Morassi, Rosset (2004).

- $\Omega$  elastic body,  $D$  rigid inclusion,

Morassi, Rosset (2009).

- $\Omega$  fluid container,  $D$  immersed body,

Alvarez, Conca, Friz, Kavian, Ortega (2005), Doubova,  
Fernández-Cara, González-Burgos, Ortega (2006),  
Doubova, Fernández-Cara, Ortega (2007), Ballerini (2010).

# A family of problems

## Introduction

Insulating  
cavity in a  
conductor.

Strategy for  
uniqueness.

Tools for stability.

Cavity with  
boundary  
impedance.

Rigid inclusion  
in an elastic  
body.

End.

- $\Omega$  elastic body,  $D$  cavity,

Higashimori (2002), Morassi, Rosset (2004).

- $\Omega$  elastic body,  $D$  rigid inclusion,

Morassi, Rosset (2009).

- $\Omega$  fluid container,  $D$  immersed body,

Alvarez, Conca, Friz, Kavian, Ortega (2005), Doubova,  
Fernández-Cara, González-Burgos, Ortega (2006),  
Doubova, Fernández-Cara, Ortega (2007), Ballerini (2010).

# A family of problems

## Introduction

Insulating  
cavity in a  
conductor.

Strategy for  
uniqueness.

Tools for stability.

Cavity with  
boundary  
impedance.

Rigid inclusion  
in an elastic  
body.

End.

- $\Omega$  elastic body,  $D$  cavity,

Higashimori (2002), Morassi, Rosset (2004).

- $\Omega$  elastic body,  $D$  rigid inclusion,

Morassi, Rosset (2009).

- $\Omega$  fluid container,  $D$  immersed body,

Alvarez, Conca, Friz, Kavian, Ortega (2005), Doubova,  
Fernández-Cara, González-Burgos, Ortega (2006),  
Doubova, Fernández-Cara, Ortega (2007), Ballerini (2010).

# The prototype.

insulating cavity in a conductor

Assume  $\Omega \setminus \bar{D}$  connected.

$$\begin{cases} \Delta u = 0, & \text{in } \Omega \setminus \bar{D}, \\ \nabla u \cdot \nu = 0, & \text{on } \partial D, \\ \nabla u \cdot \nu = \psi, & \text{on } \partial\Omega. \end{cases}$$

$\nu$  exterior unit normal to  $\partial(\Omega \setminus \bar{D})$ .  $\int_{\partial\Omega} \psi = 0$ .

Find  $D$  given  $u|_{\partial\Omega}$ .

# The prototype.

insulating cavity in a conductor

Assume  $\Omega \setminus \overline{D}$  connected.

$$\begin{cases} \Delta u = 0, & \text{in } \Omega \setminus \overline{D}, \\ \nabla u \cdot \nu = 0, & \text{on } \partial D, \\ \nabla u \cdot \nu = \psi, & \text{on } \partial \Omega. \end{cases}$$

$\nu$  exterior unit normal to  $\partial(\Omega \setminus \overline{D})$ .  $\int_{\partial \Omega} \psi = 0$ .

Find  $D$  given  $u|_{\partial \Omega}$ .



# The prototype.

insulating cavity in a conductor

Assume  $\Omega \setminus \bar{D}$  connected.

$$\begin{cases} \Delta u = 0, & \text{in } \Omega \setminus \bar{D}, \\ \nabla u \cdot \nu = 0, & \text{on } \partial D, \\ \nabla u \cdot \nu = \psi, & \text{on } \partial\Omega. \end{cases}$$

$\nu$  exterior unit normal to  $\partial(\Omega \setminus \bar{D})$ .  $\int_{\partial\Omega} \psi = 0$ .

Find  $D$  given  $u|_{\partial\Omega}$ .

# The prototype.

instability

A.-Rondi (2001). Let  $n = 2$ ,  $\Omega = B_1(0)$ ,  $D_0 = B_{1/2}(0)$ ,  
denote  $z = x + iy$  and

$$f_k(z) = z \exp[\epsilon_k(z^k - z^{-k})], z \neq 0,$$

with

$$\epsilon_k = O(k^{-M}2^{-k}) \in \mathbb{R}, k = 1, 2, \dots$$

denote  $D_k = f(D_0)$ . Then  $D_k$  are uniformly  $C^M$ -smooth and

# The prototype.

instability

A.-Rondi (2001). Let  $n = 2$ ,  $\Omega = B_1(0)$ ,  $D_0 = B_{1/2}(0)$ ,  
denote  $z = x + iy$  and

$$f_k(z) = z \exp[\epsilon_k(z^k - z^{-k})], z \neq 0,$$

with

$$\epsilon_k = O(k^{-M}2^{-k}) \in \mathbb{R}, k = 1, 2, \dots$$

denote  $D_k = f(D_0)$ . Then  $D_k$  are uniformly  $C^M$ -smooth and

# The prototype.

instability

$$d_{\mathcal{H}}(\partial D_0, \partial D_k) \sim k^{-M} \rightarrow 0 \text{ polynomially ,}$$

whereas,

letting  $u_k$  be the potential corresponding to  $D_k$ ,  $k = 0, 1, \dots$

$$\|u_k - u_0\|_{L^2(\partial\Omega)} \sim \epsilon_k^{1/2} \rightarrow 0 \text{ exponentially .}$$

# The prototype.

instability

$$d_{\mathcal{H}}(\partial D_0, \partial D_k) \sim k^{-M} \rightarrow 0 \text{ polynomially ,}$$

whereas,

letting  $u_k$  be the potential corresponding to  $D_k$ ,  $k = 0, 1, \dots$

$$\|u_k - u_0\|_{L^2(\partial\Omega)} \sim \epsilon_k^{1/2} \rightarrow 0 \text{ exponentially .}$$

## Strategy for uniqueness.

Given two cavities  $D_1, D_2$ , and given a nontrivial boundary current density  $\psi$ , let  $u_1, u_2$  solve for  $i = 1, 2$

$$\begin{cases} \Delta u_i = 0, & \text{in } \Omega \setminus \overline{D_i}, \\ \nabla u_i \cdot \nu = 0, & \text{on } \partial D_i, \\ \nabla u_i \cdot \nu = \psi, & \text{on } \partial \Omega, \end{cases}$$

and suppose  $D_1, D_2$  give rise to the same potential on  $\partial \Omega$ :

$$u_1|_{\partial \Omega} = u_2|_{\partial \Omega}.$$

If we had  $D_1 \neq D_2$ , we might assume w.l.o.g.  $D_2 \setminus \overline{D_1} \neq \emptyset$ .

## Strategy for uniqueness.

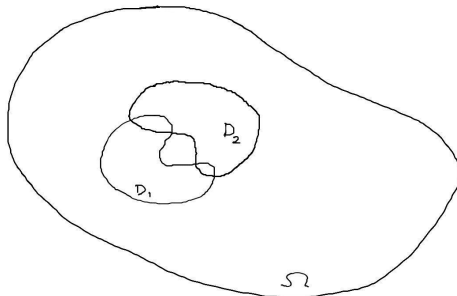


Figure: two cavities.

## Strategy for uniqueness.

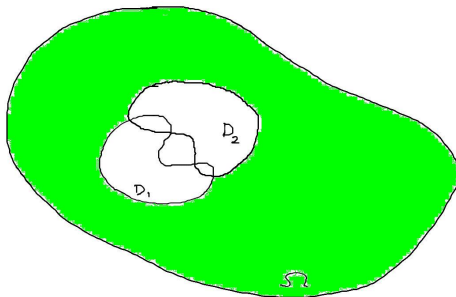


Figure: the set  $G$ .

$G$ : connected component of  $\Omega \setminus (\overline{D_1 \cup D_2})$  such that  $\partial\Omega \subset \partial G$ .



## Strategy for uniqueness.

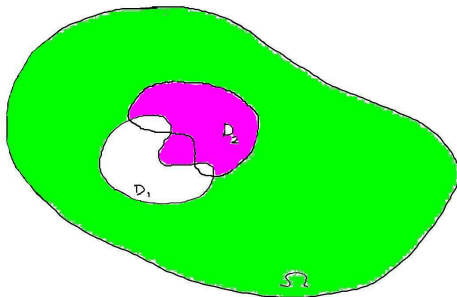


Figure: the set  $E_2 \supset D_2 \setminus \overline{D_1}$ .

$$E_2 = \Omega \setminus \overline{D_1 \cup G}$$

$$\partial E_2 = \Gamma_1 \cup \Gamma_2, \Gamma_1 \subset (\partial D_1 \setminus G), \Gamma_2 \subset (\partial D_2 \cap \partial G).$$

## Strategy for uniqueness.

$u_1, u_2$  have the same Cauchy data on  $\partial\Omega$ :

$$\nabla u_1 \cdot \nu = \nabla u_2 \cdot \nu = \psi \text{ and } u_1 = u_2 \text{ on } \partial\Omega.$$

Hence, by **unique continuation**,

$$u_1 \equiv u_2 \text{ in } G,$$



$$\nabla u_1 \cdot \nu = \nabla u_2 \cdot \nu = 0 \text{ on } \Gamma_2 \subset (\partial D_2 \cap \partial G)$$

Therefore

$$\begin{aligned} \int_{D_2 \setminus \overline{D_1}} |\nabla u_1|^2 &\leq \int_{E_2} |\nabla u_1|^2 \leq \\ &\leq \int_{\Gamma_1} |u_1 \nabla u_1 \cdot \nu| + \int_{\Gamma_2} |u_1 \nabla u_2 \cdot \nu| = 0. \end{aligned}$$

## Strategy for uniqueness.

$u_1, u_2$  have the same Cauchy data on  $\partial\Omega$ :

$$\nabla u_1 \cdot \nu = \nabla u_2 \cdot \nu = \psi \text{ and } u_1 = u_2 \text{ on } \partial\Omega.$$

Hence, by **unique continuation**,

$$u_1 \equiv u_2 \text{ in } G,$$



$$\nabla u_1 \cdot \nu = \nabla u_2 \cdot \nu = 0 \text{ on } \Gamma_2 \subset (\partial D_2 \cap \partial G)$$

Therefore

$$\begin{aligned} \int_{D_2 \setminus \overline{D_1}} |\nabla u_1|^2 &\leq \int_{E_2} |\nabla u_1|^2 \leq \\ &\leq \int_{\Gamma_1} |u_1 \nabla u_1 \cdot \nu| + \int_{\Gamma_2} |u_1 \nabla u_2 \cdot \nu| = 0. \end{aligned}$$

## Strategy for uniqueness.

$u_1, u_2$  have the same Cauchy data on  $\partial\Omega$ :

$$\nabla u_1 \cdot \nu = \nabla u_2 \cdot \nu = \psi \text{ and } u_1 = u_2 \text{ on } \partial\Omega.$$

Hence, by **unique continuation**,

$$u_1 \equiv u_2 \text{ in } G,$$

$\Downarrow$

$$\nabla u_1 \cdot \nu = \nabla u_2 \cdot \nu = 0 \text{ on } \Gamma_2 \subset (\partial D_2 \cap \partial G)$$

Therefore

$$\begin{aligned} \int_{D_2 \setminus \overline{D_1}} |\nabla u_1|^2 &\leq \int_{E_2} |\nabla u_1|^2 \leq \\ &\leq \int_{\Gamma_1} |u_1 \nabla u_1 \cdot \nu| + \int_{\Gamma_2} |u_1 \nabla u_2 \cdot \nu| = 0. \end{aligned}$$

## Strategy for uniqueness.

$u_1, u_2$  have the same Cauchy data on  $\partial\Omega$ :

$$\nabla u_1 \cdot \nu = \nabla u_2 \cdot \nu = \psi \text{ and } u_1 = u_2 \text{ on } \partial\Omega.$$

Hence, by **unique continuation**,

$$u_1 \equiv u_2 \text{ in } G,$$

$\Downarrow$

$$\nabla u_1 \cdot \nu = \nabla u_2 \cdot \nu = 0 \text{ on } \Gamma_2 \subset (\partial D_2 \cap \partial G)$$

Therefore

$$\begin{aligned} \int_{D_2 \setminus \overline{D_1}} |\nabla u_1|^2 &\leq \int_{E_2} |\nabla u_1|^2 \leq \\ &\leq \int_{\Gamma_1} |u_1 \nabla u_1 \cdot \nu| + \int_{\Gamma_2} |u_1 \nabla u_2 \cdot \nu| = 0. \end{aligned}$$

# Strategy for uniqueness.

Either:

$u_1 \equiv \text{constant}$  on an open set

unique continuation



$$\psi \equiv 0,$$

or

$$D_2 \setminus \overline{D_1} = \emptyset.$$

# Strategy for uniqueness.

Either:

$u_1 \equiv \text{constant}$  on an open set

unique continuation



$$\psi \equiv 0,$$

or

$$D_2 \setminus \overline{D_1} = \emptyset.$$

# Strategy for uniqueness.

Either:

$u_1 \equiv \text{constant}$  on an open set

unique continuation



$$\psi \equiv 0,$$

or

$$D_2 \setminus \overline{D_1} = \emptyset.$$



# Tools for stability.

- Assume a-priori  $C^{1,\alpha}$  bounds on  $\partial D_1$ ,  $\partial D_2$  and on  $\partial\Omega$ .
- Assume  $\psi$  nontrivial:

$$\frac{\|\psi\|_{L^2(\partial\Omega)}}{\|\psi\|_{H^{-1/2}(\partial\Omega)}} \leq F.$$

- Assume

$$\|u_1 - u_2\|_{L^2(\partial\Omega)} \leq \epsilon.$$

## Tools for stability.

- Assume a-priori  $C^{1,\alpha}$  bounds on  $\partial D_1$ ,  $\partial D_2$  and on  $\partial\Omega$ .
- Assume  $\psi$  nontrivial:

$$\frac{\|\psi\|_{L^2(\partial\Omega)}}{\|\psi\|_{H^{-1/2}(\partial\Omega)}} \leq F.$$

- Assume

$$\|u_1 - u_2\|_{L^2(\partial\Omega)} \leq \epsilon.$$

## Tools for stability.

- Assume a-priori  $C^{1,\alpha}$  bounds on  $\partial D_1$ ,  $\partial D_2$  and on  $\partial\Omega$ .
- Assume  $\psi$  nontrivial:

$$\frac{\|\psi\|_{L^2(\partial\Omega)}}{\|\psi\|_{H^{-1/2}(\partial\Omega)}} \leq F.$$

- Assume

$$\|u_1 - u_2\|_{L^2(\partial\Omega)} \leq \epsilon.$$

## Tools for stability.

- Assume a-priori  $C^{1,\alpha}$  bounds on  $\partial D_1, \partial D_2$  and on  $\partial\Omega$ .
- Assume  $\psi$  nontrivial:

$$\frac{\|\psi\|_{L^2(\partial\Omega)}}{\|\psi\|_{H^{-1/2}(\partial\Omega)}} \leq F.$$

- Assume

$$\|u_1 - u_2\|_{L^2(\partial\Omega)} \leq \epsilon.$$

## Tools for stability.

step 1

Stability for a Cauchy problem in  $G$ .

$$\int_{D_2 \setminus \overline{D_1}} |\nabla u_1|^2 \leq \omega^{(2)}(\epsilon)$$

where  $\omega^{(2)}(\epsilon) = \omega \circ \omega(\epsilon)$  and

$$\omega(\epsilon) \sim |\log \epsilon|^{-\gamma}, \text{ as } \epsilon \rightarrow 0.$$

Improved stability for a Cauchy problem in  $G$ .  
If in addition,  $G$  is known to be Lipschitz, then

$$\int_{D_2 \setminus \overline{D_1}} |\nabla u_1|^2 \leq \omega(\epsilon)$$

# Tools for stability.

step 1

Stability for a Cauchy problem in  $G$ .

$$\int_{D_2 \setminus \overline{D_1}} |\nabla u_1|^2 \leq \omega^{(2)}(\epsilon)$$

where  $\omega^{(2)}(\epsilon) = \omega \circ \omega(\epsilon)$  and

$$\omega(\epsilon) \sim |\log \epsilon|^{-\gamma}, \text{ as } \epsilon \rightarrow 0.$$

Improved stability for a Cauchy problem in  $G$ .  
If in addition,  $G$  is known to be Lipschitz, then

$$\int_{D_2 \setminus \overline{D_1}} |\nabla u_1|^2 \leq \omega(\epsilon)$$

# Tools for stability.

step 1

Stability for a Cauchy problem in  $G$ .

$$\int_{D_2 \setminus \overline{D_1}} |\nabla u_1|^2 \leq \omega^{(2)}(\epsilon)$$

where  $\omega^{(2)}(\epsilon) = \omega \circ \omega(\epsilon)$  and

$$\omega(\epsilon) \sim |\log \epsilon|^{-\gamma}, \text{ as } \epsilon \rightarrow 0.$$

Improved stability for a Cauchy problem in  $G$ .  
If in addition,  $G$  is known to be Lipschitz, then

$$\int_{D_2 \setminus \overline{D_1}} |\nabla u_1|^2 \leq \omega(\epsilon)$$

# Tools for stability.

step 1

Stability for a Cauchy problem in  $G$ .

$$\int_{D_2 \setminus \overline{D_1}} |\nabla u_1|^2 \leq \omega^{(2)}(\epsilon)$$

where  $\omega^{(2)}(\epsilon) = \omega \circ \omega(\epsilon)$  and

$$\omega(\epsilon) \sim |\log \epsilon|^{-\gamma}, \text{ as } \epsilon \rightarrow 0.$$

Improved stability for a Cauchy problem in  $G$ .  
If in addition,  $G$  is known to be Lipschitz, then

$$\int_{D_2 \setminus \overline{D_1}} |\nabla u_1|^2 \leq \omega(\epsilon)$$



# Tools for stability.

step 2

## Propagation of smallness.

If, for a suitable  $s > 1$ ,  $B_{s\rho}(x) \subset \Omega \setminus \overline{D_1}$  then

$$\int_{B_\rho(x)} |\nabla u_1|^2 \geq \frac{C(F)}{\exp[A\rho^{-B}]} \int_{\Omega \setminus \overline{D_1}} |\nabla u_1|^2.$$

# Tools for stability.

step 2

Propagation of smallness.

If, for a suitable  $s > 1$ ,  $B_{s\rho}(x) \subset \Omega \setminus \overline{D_1}$  then

$$\int_{B_\rho(x)} |\nabla u_1|^2 \geq \frac{C(F)}{\exp[A\rho^{-B}]} \int_{\Omega \setminus \overline{D_1}} |\nabla u_1|^2.$$

# Tools for stability.

step 3

## Geometric argument.

$$\text{inradius}(D_2 \setminus \overline{D_1}) + \text{inradius}(D_1 \setminus \overline{D_2}) \leq \omega^{(3)}(\epsilon)$$

using the  $C^{1,\alpha}$  a-priori bound

$$d_{\mathcal{H}}(\partial D_1, \partial D_2) \leq \omega^{(3)}(\epsilon).$$

When  $\epsilon$  is small enough, then the above rough bound implies that  $G$  is Lipschitz, we can use the improved estimate for the Cauchy problem and arrive at

$$d_{\mathcal{H}}(\partial D_1, \partial D_2) \leq \omega^{(2)}(\epsilon).$$

# Tools for stability.

step 3

Geometric argument.

$$\text{inradius}(D_2 \setminus \overline{D_1}) + \text{inradius}(D_1 \setminus \overline{D_2}) \leq \omega^{(3)}(\epsilon)$$

using the  $C^{1,\alpha}$  a-priori bound

$$d_{\mathcal{H}}(\partial D_1, \partial D_2) \leq \omega^{(3)}(\epsilon).$$

When  $\epsilon$  is small enough, then the above rough bound implies that  $G$  is Lipschitz, we can use the improved estimate for the Cauchy problem and arrive at

$$d_{\mathcal{H}}(\partial D_1, \partial D_2) \leq \omega^{(2)}(\epsilon).$$

# Tools for stability.

step 3

Geometric argument.

$$\text{inradius}(D_2 \setminus \overline{D_1}) + \text{inradius}(D_1 \setminus \overline{D_2}) \leq \omega^{(3)}(\epsilon)$$

using the  $C^{1,\alpha}$  a-priori bound

$$d_{\mathcal{H}}(\partial D_1, \partial D_2) \leq \omega^{(3)}(\epsilon).$$

When  $\epsilon$  is small enough, then the above rough bound implies that  $G$  is Lipschitz, we can use the improved estimate for the Cauchy problem and arrive at

$$d_{\mathcal{H}}(\partial D_1, \partial D_2) \leq \omega^{(2)}(\epsilon).$$

# Tools for stability.

step 3

Geometric argument.

$$\text{inradius}(D_2 \setminus \overline{D_1}) + \text{inradius}(D_1 \setminus \overline{D_2}) \leq \omega^{(3)}(\epsilon)$$

using the  $C^{1,\alpha}$  a-priori bound

$$d_{\mathcal{H}}(\partial D_1, \partial D_2) \leq \omega^{(3)}(\epsilon).$$

When  $\epsilon$  is small enough, then the above rough bound implies that  $G$  is Lipschitz, we can use the improved estimate for the Cauchy problem and arrive at

$$d_{\mathcal{H}}(\partial D_1, \partial D_2) \leq \omega^{(2)}(\epsilon).$$

## Tools for stability.

step 3

Geometric argument.

$$\text{inradius}(D_2 \setminus \overline{D_1}) + \text{inradius}(D_1 \setminus \overline{D_2}) \leq \omega^{(3)}(\epsilon)$$

using the  $C^{1,\alpha}$  a-priori bound

$$d_{\mathcal{H}}(\partial D_1, \partial D_2) \leq \omega^{(3)}(\epsilon).$$

When  $\epsilon$  is small enough, then the above rough bound implies that  $G$  is Lipschitz, we can use the improved estimate for the Cauchy problem and arrive at

$$d_{\mathcal{H}}(\partial D_1, \partial D_2) \leq \omega^{(2)}(\epsilon).$$

## Tools for stability.

step 4

How to improve the propagation of smallness?

Doubling at the boundary, with Neumann condition.

Adolfsson and Escauriaza (1997).

If  $\partial D_1 \in C^{1,1}$  then  $\forall x \in \partial D_1$

$$\int_{B_{2\rho} \setminus \overline{D_1}} |\nabla u_1|^2 \leq C(F) \int_{B_\rho \setminus \overline{D_1}} |\nabla u_1|^2$$

$$\Downarrow$$

$$\int_{B_\rho(x) \setminus \overline{D_1}} |\nabla u_1|^2 \geq C\rho^K \int_{\Omega \setminus \overline{D_1}} |\nabla u_1|^2.$$

with  $C, K > 0$  depending on  $F$ .



## Tools for stability.

step 4

How to improve the propagation of smallness?  
Doubling at the boundary, with Neumann condition.  
Adolfsson and Escauriaza (1997).

If  $\partial D_1 \in C^{1,1}$  then  $\forall x \in \partial D_1$

$$\int_{B_{2\rho} \setminus \overline{D_1}} |\nabla u_1|^2 \leq C(F) \int_{B_\rho \setminus \overline{D_1}} |\nabla u_1|^2$$

$$\Downarrow$$

$$\int_{B_\rho(x) \setminus \overline{D_1}} |\nabla u_1|^2 \geq C\rho^K \int_{\Omega \setminus \overline{D_1}} |\nabla u_1|^2.$$

with  $C, K > 0$  depending on  $F$ .

## Tools for stability.

step 4

How to improve the propagation of smallness?  
Doubling at the boundary, with Neumann condition.  
Adolfsson and Escauriaza (1997).

If  $\partial D_1 \in C^{1,1}$  then  $\forall x \in \partial D_1$

$$\int_{B_{2\rho} \setminus \overline{D_1}} |\nabla u_1|^2 \leq C(F) \int_{B_\rho \setminus \overline{D_1}} |\nabla u_1|^2$$



$$\int_{B_\rho(x) \setminus \overline{D_1}} |\nabla u_1|^2 \geq C\rho^K \int_{\Omega \setminus \overline{D_1}} |\nabla u_1|^2.$$

with  $C, K > 0$  depending on  $F$ .

## Tools for stability.

step 4

How to improve the propagation of smallness?  
Doubling at the boundary, with Neumann condition.  
Adolfsson and Escauriaza (1997).

If  $\partial D_1 \in C^{1,1}$  then  $\forall x \in \partial D_1$

$$\int_{B_{2\rho} \setminus \overline{D_1}} |\nabla u_1|^2 \leq C(F) \int_{B_\rho \setminus \overline{D_1}} |\nabla u_1|^2$$

$$\Downarrow$$

$$\int_{B_\rho(x) \setminus \overline{D_1}} |\nabla u_1|^2 \geq C\rho^K \int_{\Omega \setminus \overline{D_1}} |\nabla u_1|^2.$$

with  $C, K > 0$  depending on  $F$ .

# Tools for stability.

conclusion

In summary:  
we obtain

$$d_{\mathcal{H}}(\partial D_1, \partial D_2) \leq \omega^{(2)}(\epsilon).$$

using

stability for the Cauchy pb. and propagation of smallness



three spheres inequality

If we also have the

doubling inequality at the boundary

then we arrive at

$$d_{\mathcal{H}}(\partial D_1, \partial D_2) \leq \omega(\epsilon).$$

# Tools for stability.

conclusion

In summary:  
we obtain

$$d_{\mathcal{H}}(\partial D_1, \partial D_2) \leq \omega^{(2)}(\epsilon).$$

using

stability for the Cauchy pb. and propagation of smallness



three spheres inequality

If we also have the

doubling inequality at the boundary

then we arrive at

$$d_{\mathcal{H}}(\partial D_1, \partial D_2) \leq \omega(\epsilon).$$

# Tools for stability.

conclusion

In summary:  
we obtain

$$d_{\mathcal{H}}(\partial D_1, \partial D_2) \leq \omega^{(2)}(\epsilon).$$

using

stability for the Cauchy pb. and propagation of smallness



three spheres inequality

If we also have the

doubling inequality at the boundary

then we arrive at

$$d_{\mathcal{H}}(\partial D_1, \partial D_2) \leq \omega(\epsilon).$$

A., Beretta, Rosset, Vessella (2000).

# Tools for stability.

conclusion

In summary:  
we obtain

$$d_{\mathcal{H}}(\partial D_1, \partial D_2) \leq \omega^{(2)}(\epsilon).$$

using

stability for the Cauchy pb. and propagation of smallness



three spheres inequality

If we also have the

doubling inequality at the boundary

then we arrive at

$$d_{\mathcal{H}}(\partial D_1, \partial D_2) \leq \omega(\epsilon).$$

A., Beretta, Rosset, Vessella (2000).

# Tools for stability.

conclusion

In summary:  
we obtain

$$d_{\mathcal{H}}(\partial D_1, \partial D_2) \leq \omega^{(2)}(\epsilon).$$

using

stability for the Cauchy pb. and propagation of smallness



three spheres inequality

If we also have the

doubling inequality at the boundary

then we arrive at

$$d_{\mathcal{H}}(\partial D_1, \partial D_2) \leq \omega(\epsilon).$$



# Tools for stability.

conclusion

In summary:  
we obtain

$$d_{\mathcal{H}}(\partial D_1, \partial D_2) \leq \omega^{(2)}(\epsilon).$$

using

stability for the Cauchy pb. and propagation of smallness



three spheres inequality

If we also have the

doubling inequality at the boundary

then we arrive at

$$d_{\mathcal{H}}(\partial D_1, \partial D_2) \leq \omega(\epsilon).$$

A., Beretta, Rosset, Vessella (2000).

# Tools for stability.

the three spheres inequality

For every  $0 < r_1 < r_2 < r_3$

$$\int_{B_{r_2}} |u|^2 \leq C \left( \int_{B_{r_1}} |u|^2 \right)^\alpha \left( \int_{B_{r_3}} |u|^2 \right)^{1-\alpha}$$

with  $C > 0, 0 < \alpha < 1$  only depending on  $\frac{r_2}{r_1}, \frac{r_3}{r_2}$ .

## Cavity with impedance.

$$\begin{cases} \Delta u = 0, & \text{in } \Omega \setminus \bar{D}, \\ \nabla u \cdot \nu + \gamma u = 0, & \text{on } \partial D, \\ \nabla u \cdot \nu = \psi, & \text{on } \partial \Omega. \end{cases} \quad \gamma \geq 0$$

$\nu$  exterior unit normal to  $\partial(\Omega \setminus \bar{D})$ .

- Non-uniqueness: one pair of Cauchy data  $(\psi, u|_{\partial\Omega})$  does not suffice to uniquely determine  $D$  (and  $\gamma$ ). Cakoni, Kress (2007), Rundell (2008).
- Uniqueness: two pairs of Cauchy data  $(\psi, u|_{\partial\Omega})$  and  $(\tilde{\psi}, \tilde{u}|_{\partial\Omega})$ , with linearly independent  $\psi, \tilde{\psi}$  and  $\psi \geq 0$  uniquely determine  $D$  and  $\gamma$ . Bacchelli (2009), Pagani, Pierotti (2009).
- Stability: with two such pairs there is *log*-stability. Sincich (2010).

## Cavity with impedance.

$$\begin{cases} \Delta u = 0, & \text{in } \Omega \setminus \bar{D}, \\ \nabla u \cdot \nu + \gamma u = 0, & \text{on } \partial D, \\ \nabla u \cdot \nu = \psi, & \text{on } \partial \Omega. \end{cases} \quad \gamma \geq 0$$

$\nu$  exterior unit normal to  $\partial(\Omega \setminus \bar{D})$ .

- **Non-uniqueness:** one pair of Cauchy data  $(\psi, u|_{\partial\Omega})$  does not suffice to uniquely determine  $D$  (and  $\gamma$ ). Cakoni, Kress (2007), Rundell (2008).
- **Uniqueness:** two pairs of Cauchy data  $(\psi, u|_{\partial\Omega})$  and  $(\tilde{\psi}, \tilde{u}|_{\partial\Omega})$ , with linearly independent  $\psi, \tilde{\psi}$  and  $\psi \geq 0$  uniquely determine  $D$  and  $\gamma$ . Bacchelli (2009), Pagani, Pierotti (2009).
- **Stability:** with two such pairs there is *log*-stability. Sincich (2010).

## Cavity with impedance.

$$\begin{cases} \Delta u = 0, & \text{in } \Omega \setminus \bar{D}, \\ \nabla u \cdot \nu + \gamma u = 0, & \text{on } \partial D, \\ \nabla u \cdot \nu = \psi, & \text{on } \partial \Omega. \end{cases} \quad \gamma \geq 0$$

$\nu$  exterior unit normal to  $\partial(\Omega \setminus \bar{D})$ .

- Non-uniqueness: one pair of Cauchy data  $(\psi, u|_{\partial\Omega})$  does not suffice to uniquely determine  $D$  (and  $\gamma$ ). Cakoni, Kress (2007), Rundell (2008).
- Uniqueness: two pairs of Cauchy data  $(\psi, u|_{\partial\Omega})$  and  $(\tilde{\psi}, \tilde{u}|_{\partial\Omega})$ , with linearly independent  $\psi, \tilde{\psi}$  and  $\psi \geq 0$  uniquely determine  $D$  and  $\gamma$ . Bacchelli (2009), Pagani, Pierotti (2009).
- Stability: with two such pairs there is *log*-stability. Sincich (2010).

## Cavity with impedance.

$$\begin{cases} \Delta u = 0, & \text{in } \Omega \setminus \bar{D}, \\ \nabla u \cdot \nu + \gamma u = 0, & \text{on } \partial D, \\ \nabla u \cdot \nu = \psi, & \text{on } \partial \Omega. \end{cases} \quad \gamma \geq 0$$

$\nu$  exterior unit normal to  $\partial(\Omega \setminus \bar{D})$ .

- Non-uniqueness: one pair of Cauchy data  $(\psi, u|_{\partial\Omega})$  does not suffice to uniquely determine  $D$  (and  $\gamma$ ). Cakoni, Kress (2007), Rundell (2008).
- Uniqueness: two pairs of Cauchy data  $(\psi, u|_{\partial\Omega})$  and  $(\tilde{\psi}, \tilde{u}|_{\partial\Omega})$ , with linearly independent  $\psi, \tilde{\psi}$  and  $\psi \geq 0$  uniquely determine  $D$  and  $\gamma$ . Bacchelli (2009), Pagani, Pierotti (2009).
- Stability: with two such pairs there is *log*-stability. Sincich (2010).

# Cavity with impedance.

what goes wrong?

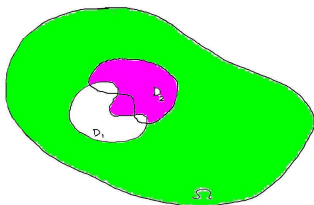


Figure: the set  $E_2 \supset D_2 \setminus \overline{D_1}$ .

$$\begin{cases} \Delta u_1 = 0, & \text{in } E_2, \\ \nabla u_1 \cdot \nu + \gamma_1 u_1 = 0, & \text{on } \partial E_2 \cap \partial D_1, \\ -\nabla u_1 \cdot \nu + \gamma_2 u_1 = 0, & \text{on } \partial E_2 \cap \partial D_2, \end{cases}$$

$\nu$  exterior unit normal to  $E_2$ .

# Cavity with impedance.

the approach by Sincich

Let  $u_i$  be the potential corresponding to  $D_i$ ,  $i = 1, 2$ .  
If  $\psi \not\equiv 0$  then (strong maximum principle)  $u_i > 0$ .

Set

$$v_i = \frac{\tilde{u}_i}{u_i},$$

then

$$\begin{cases} \operatorname{div}(u_i^2 \nabla v_i) = 0, & \text{in } \Omega \setminus \overline{D_i}, \\ u_i^2 \nabla v_i \cdot \nu = 0, & \text{on } \partial D_i, \\ u_i^2 \nabla v_i \cdot \nu = u_i \tilde{\psi} - \tilde{u}_i \psi, & \text{on } \partial \Omega. \end{cases}$$



## Cavity with impedance.

the approach by Sincich

Let  $u_i$  be the potential corresponding to  $D_i$ ,  $i = 1, 2$ .

If  $\psi \not\equiv 0$  then (strong maximum principle)  $u_i > 0$ .

Set

$$v_i = \frac{\tilde{u}_i}{u_i},$$

then

$$\begin{cases} \operatorname{div}(u_i^2 \nabla v_i) = 0, & \text{in } \Omega \setminus \overline{D_i}, \\ u_i^2 \nabla v_i \cdot \nu = 0, & \text{on } \partial D_i, \\ u_i^2 \nabla v_i \cdot \nu = u_i \tilde{\psi} - \tilde{u}_i \psi, & \text{on } \partial \Omega. \end{cases}$$

# Cavity with impedance.

open problem

What if both  $\psi, \tilde{\psi}$  change sign?

## Rigid inclusion in elastic body.

In  $\mathbb{R}^3$  (or  $\mathbb{R}^2$ ).

$$\begin{cases} \operatorname{div}(\mu(\nabla u + \nabla u^T)) + \nabla(\lambda \operatorname{div} u) = 0, & \text{in } \Omega \setminus \bar{D}, \\ u \in \mathcal{R}, & \text{on } \partial D, \\ (\mu(\nabla u + \nabla u^T) + (\lambda \operatorname{div} u)I)\nu = \psi, & \text{on } \partial\Omega. \end{cases}$$

Lamè parameters  $\mu, \lambda \in C^{1,1}$  satisfying strong convexity  
 $\mu \geq \alpha > 0, 2\mu + 3\lambda \geq \beta > 0$ .

$$\begin{aligned} \mathcal{R} &= \text{space of infinitesimal rigid displacements} = \\ &= \{r(x) \mid r(x) = c + Wx, c \in \mathbb{R}^3, W + W^T = 0\} \end{aligned}$$

+ equilibrium condition

$$\int_{\partial D} (\mu(\nabla u + \nabla u^T) + (\lambda \operatorname{div} u)I)\nu \cdot r = 0 \quad \forall r \in \mathcal{R}$$

## Rigid inclusion in elastic body.

In  $\mathbb{R}^3$  (or  $\mathbb{R}^2$ ).

$$\begin{cases} \operatorname{div}(\mu(\nabla u + \nabla u^T)) + \nabla(\lambda \operatorname{div} u) = 0, & \text{in } \Omega \setminus \bar{D}, \\ u \in \mathcal{R}, & \text{on } \partial D, \\ (\mu(\nabla u + \nabla u^T) + (\lambda \operatorname{div} u)I)\nu = \psi, & \text{on } \partial\Omega. \end{cases}$$

Lamè parameters  $\mu, \lambda \in C^{1,1}$  satisfying strong convexity  
 $\mu \geq \alpha > 0, 2\mu + 3\lambda \geq \beta > 0$ .

$$\begin{aligned} \mathcal{R} &= \text{space of infinitesimal rigid displacements} = \\ &= \{r(x) \mid r(x) = c + Wx, c \in \mathbb{R}^3, W + W^T = 0\} \end{aligned}$$

+ equilibrium condition

$$\int_{\partial D} (\mu(\nabla u + \nabla u^T) + (\lambda \operatorname{div} u)I)\nu \cdot r = 0 \quad \forall r \in \mathcal{R}$$

## Rigid inclusion in elastic body.

In  $\mathbb{R}^3$  (or  $\mathbb{R}^2$ ).

$$\begin{cases} \operatorname{div}(\mu(\nabla u + \nabla u^T)) + \nabla(\lambda \operatorname{div} u) = 0, & \text{in } \Omega \setminus \bar{D}, \\ u \in \mathcal{R}, & \text{on } \partial D, \\ (\mu(\nabla u + \nabla u^T) + (\lambda \operatorname{div} u)I)\nu = \psi, & \text{on } \partial\Omega. \end{cases}$$

Lamè parameters  $\mu, \lambda \in C^{1,1}$  satisfying strong convexity  
 $\mu \geq \alpha > 0, 2\mu + 3\lambda \geq \beta > 0$ .

$$\begin{aligned} \mathcal{R} &= \text{space of infinitesimal rigid displacements} = \\ &= \{r(x) \mid r(x) = c + Wx, c \in \mathbb{R}^3, W + W^T = 0\} \end{aligned}$$

+ equilibrium condition

$$\int_{\partial D} (\mu(\nabla u + \nabla u^T) + (\lambda \operatorname{div} u)I)\nu \cdot r = 0 \quad \forall r \in \mathcal{R}$$

## Rigid inclusion in elastic body.

In  $\mathbb{R}^3$  (or  $\mathbb{R}^2$ ).

$$\begin{cases} \operatorname{div}(\mu(\nabla u + \nabla u^T)) + \nabla(\lambda \operatorname{div} u) = 0, & \text{in } \Omega \setminus \bar{D}, \\ u \in \mathcal{R}, & \text{on } \partial D, \\ (\mu(\nabla u + \nabla u^T) + (\lambda \operatorname{div} u)I)\nu = \psi, & \text{on } \partial\Omega. \end{cases}$$

Lamè parameters  $\mu, \lambda \in C^{1,1}$  satisfying strong convexity  
 $\mu \geq \alpha > 0, 2\mu + 3\lambda \geq \beta > 0$ .

$$\begin{aligned} \mathcal{R} &= \text{space of infinitesimal rigid displacements} = \\ &= \{r(x) \mid r(x) = c + Wx, c \in \mathbb{R}^3, W + W^T = 0\} \end{aligned}$$

+ equilibrium condition

$$\int_{\partial D} (\mu(\nabla u + \nabla u^T) + (\lambda \operatorname{div} u)I)\nu \cdot r = 0 \quad \forall r \in \mathcal{R}$$

## Rigid inclusion in elastic body.

In  $\mathbb{R}^3$  (or  $\mathbb{R}^2$ ).

$$\begin{cases} \operatorname{div}(\mu(\nabla u + \nabla u^T)) + \nabla(\lambda \operatorname{div} u) = 0, & \text{in } \Omega \setminus \bar{D}, \\ u \in \mathcal{R}, & \text{on } \partial D, \\ (\mu(\nabla u + \nabla u^T) + (\lambda \operatorname{div} u)I)\nu = \psi, & \text{on } \partial\Omega. \end{cases}$$

Lamè parameters  $\mu, \lambda \in C^{1,1}$  satisfying strong convexity  
 $\mu \geq \alpha > 0, 2\mu + 3\lambda \geq \beta > 0$ .

$$\begin{aligned} \mathcal{R} &= \text{space of infinitesimal rigid displacements} = \\ &= \{r(x) \mid r(x) = c + Wx, c \in \mathbb{R}^3, W + W^T = 0\} \end{aligned}$$

+ equilibrium condition

$$\int_{\partial D} (\mu(\nabla u + \nabla u^T) + (\lambda \operatorname{div} u)I)\nu \cdot r = 0 \quad \forall r \in \mathcal{R}$$

# Rigid inclusion in elastic body.

**Inverse problem: given  $u|_{\partial\Omega}$  find  $D$ .**

Morassi and Rosset (2009): uniqueness and *log – log* stability.

Let  $u_j$  be the displacement field corresponding to  $D_j, j = 1, 2$ , we have  $u_j = r_j \in \mathcal{R}$ , with  $r_j$  unknown possibly different.



## Rigid inclusion in elastic body.

Inverse problem: given  $u|_{\partial\Omega}$  find  $D$ .

Morassi and Rosset (2009): uniqueness and  $\log - \log$  stability.

Let  $u_j$  be the displacement field corresponding to  $D_j, j = 1, 2$ , we have  $u_j = r_j \in \mathcal{R}$ , with  $r_j$  unknown possibly different.

## Rigid inclusion in elastic body.

Inverse problem: given  $u|_{\partial\Omega}$  find  $D$ .

Morassi and Rosset (2009): uniqueness and  $\log - \log$  stability.

Let  $u_j$  be the displacement field corresponding to  $D_j, j = 1, 2$ , we have  $u_j = r_j \in \mathcal{R}$ , with  $r_j$  unknown possibly different.

## Rigid inclusion in elastic body.

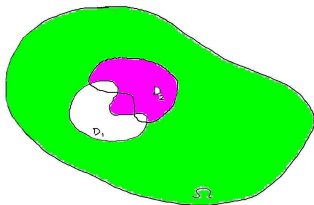


Figure: the set  $E_2 \supset D_2 \setminus \overline{D_1}$ .

$$\begin{cases} \operatorname{div}(\mu(\nabla u_1 + \nabla u_1^T)) + \nabla(\lambda \operatorname{div} u_1) = 0, & \text{in } E_2, \\ u_1 = r_1, & \text{on } \partial E_2 \cap \partial D_1, \\ u_1 = r_2, & \text{on } \partial E_2 \cap \partial D_2, \end{cases}$$

# Rigid inclusion in elastic body.

## Two cases

- 1  $\partial E_2 \cap \partial D_1 \cap \partial D_2$  contains at least three points **not aligned**.
  - 2  $\partial E_2 \cap \partial D_1 \cap \partial D_2 \subset \text{segment}$ .
- 
- 1  $r_1 = r_2 \Rightarrow u_1 \equiv r_2$  in  $E_2$ .
  - 2 **topological argument**  $\Rightarrow D_1 \subset D_2$  (or viceversa).  
Equilibrium condition + Korn inequality  $\Rightarrow u_1 \equiv r_2$ .

# Rigid inclusion in elastic body.

## Two cases

①  $\partial E_2 \cap \partial D_1 \cap \partial D_2$  contains at least three points **not aligned**.

②  $\partial E_2 \cap \partial D_1 \cap \partial D_2 \subset \text{segment}$ .

①  $r_1 = r_2 \Rightarrow u_1 \equiv r_2$  in  $E_2$ .

② **topological argument**  $\Rightarrow D_1 \subset D_2$  (or viceversa).

Equilibrium condition + Korn inequality  $\Rightarrow u_1 \equiv r_2$ .

# Rigid inclusion in elastic body.

## Two cases

①  $\partial E_2 \cap \partial D_1 \cap \partial D_2$  contains at least three points **not aligned**.

②  $\partial E_2 \cap \partial D_1 \cap \partial D_2 \subset \text{segment}$ .

①  $r_1 = r_2 \Rightarrow u_1 \equiv r_2$  in  $E_2$ .

② **topological argument**  $\Rightarrow D_1 \subset D_2$  (or viceversa).

Equilibrium condition + Korn inequality  $\Rightarrow u_1 \equiv r_2$ .

# Rigid inclusion in elastic body.

Introduction

Insulating  
cavity in a  
conductor.

Strategy for  
uniqueness.

Tools for stability.

Cavity with  
boundary  
impedance.

Rigid inclusion  
in an elastic  
body.

End.

## Two cases

- 1  $\partial E_2 \cap \partial D_1 \cap \partial D_2$  contains at least three points **not aligned**.
  - 2  $\partial E_2 \cap \partial D_1 \cap \partial D_2 \subset \text{segment}$ .
- 
- 1  $r_1 = r_2 \Rightarrow u_1 \equiv r_2$  in  $E_2$ .
  - 2 **topological argument**  $\Rightarrow D_1 \subset D_2$  (or viceversa).  
Equilibrium condition + Korn inequality  $\Rightarrow u_1 \equiv r_2$ .

# Rigid inclusion in elastic body.

Introduction

Insulating  
cavity in a  
conductor.

Strategy for  
uniqueness.

Tools for stability.

Cavity with  
boundary  
impedance.

Rigid inclusion  
in an elastic  
body.

End.

## Two cases

①  $\partial E_2 \cap \partial D_1 \cap \partial D_2$  contains at least three points **not aligned**.

②  $\partial E_2 \cap \partial D_1 \cap \partial D_2 \subset \text{segment}$ .

①  $r_1 = r_2 \Rightarrow u_1 \equiv r_2$  in  $E_2$ .

② **topological argument**  $\Rightarrow D_1 \subset D_2$  (or viceversa).

Equilibrium condition + Korn inequality  $\Rightarrow u_1 \equiv r_2$ .



# Rigid inclusion in elastic body.

Introduction

Insulating  
cavity in a  
conductor.

Strategy for  
uniqueness.

Tools for stability.

Cavity with  
boundary  
impedance.

Rigid inclusion  
in an elastic  
body.

End.

## Two cases

- 1  $\partial E_2 \cap \partial D_1 \cap \partial D_2$  contains at least three points **not aligned**.
  - 2  $\partial E_2 \cap \partial D_1 \cap \partial D_2 \subset \text{segment}$ .
- 
- 1  $r_1 = r_2 \Rightarrow u_1 \equiv r_2$  in  $E_2$ .
  - 2 **topological argument**  $\Rightarrow D_1 \subset D_2$  (or viceversa).  
Equilibrium condition + Korn inequality  $\Rightarrow u_1 \equiv r_2$ .

# Rigid inclusion in elastic body.

Introduction

Insulating  
cavity in a  
conductor.

Strategy for  
uniqueness.

Tools for stability.

Cavity with  
boundary  
impedance.

Rigid inclusion  
in an elastic  
body.

End.

## Two cases

- 1  $\partial E_2 \cap \partial D_1 \cap \partial D_2$  contains at least three points **not aligned**.
  - 2  $\partial E_2 \cap \partial D_1 \cap \partial D_2 \subset \text{segment}$ .
- 
- 1  $r_1 = r_2 \Rightarrow u_1 \equiv r_2$  in  $E_2$ .
  - 2 **topological argument**  $\Rightarrow D_1 \subset D_2$  (or viceversa).  
Equilibrium condition + Korn inequality  $\Rightarrow u_1 \equiv r_2$ .

# Rigid inclusions or cavities in elastic body.

open problem

## Doubling at the boundary?

Unknown  
Boundaries

Giovanni  
Alessandrini

Introduction

Insulating  
cavity in a  
conductor.

Strategy for  
uniqueness.

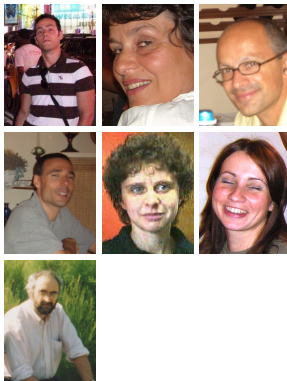
Tools for stability.

Cavity with  
boundary  
impedance.

Rigid inclusion  
in an elastic  
body.

End.

## My collaborators.



Andrea Ballerini, Elena Beretta, Antonino Morassi,  
Luca Rondi, Edi Rosset, Eva Sincich,  
Sergio Vessella.

Unknown  
Boundaries

Giovanni  
Alessandrini

Introduction

Insulating  
cavity in a  
conductor.

Strategy for  
uniqueness.

Tools for stability.

Cavity with  
boundary  
impedance.

Rigid inclusion  
in an elastic  
body.

End.

The end.



THANKS!