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### **OUTLINE**

- INFERRING PHYLOGENIES
- OPTIMIZATION PROBLEMS ON TREES
- **3** Least Square Methods
- 4 CLUSTERING METHODS

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- Inferring Phylogenies
- OPTIMIZATION PROBLEMS ON TREES
- LEAST SQUARE METHODS
- CLUSTERING METHODS

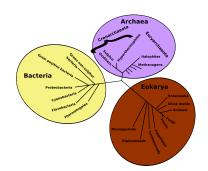
#### RECONSTRUCTING HISTORY OF LIFE

#### WHAT MEANS "PHYLOGENETIC INFERENCE"?

All species on Earth come from a common ancestor. If we have data from a pool of species, we wish to reconstruct the history of speciation events that lead to their emergence:

We want to find the phylogenetic tree giving this information!

This is an hard task, because data is often incomplete (we lack information about most of the ancestor species) and noisy.



### METHODS TO INFER PHYLOGENY

#### APPROACHES TO PHYLOGENY

- Distance-based methods
- Parsimony methods
- Likelihood methods
- Bayesian inference methods

#### **DISTANCE-BASED METHODS**

Given a matrix of pairwise distances, find the tree that explains it better. Several algorithms:

- UPGMA (clustering methods)
- Neighbor Joining
- Fitch-Margolias (sum of squares methods)

#### AN EXAMPLE: PRIMATES

#### DNA FROM PRIMATES

Tarsius AAGTTTCATTGGAGCCACCACTCTTATAATTGCCCATGGCCTCACCTCCT... Lemur AAGCTTCATAGGAGCAACCATTCTAATAATCGCACATGGCCTTACATCAT... AAGCTTCACCGGCGCAGTCATTCTCATAATCGCCCACGGGCTTACATCCT... Homo Sapiens Chimp AAGCTTCACCGGCGCAATTATCCTCATAATCGCCCACGGACTTACATCCT... Gorilla AAGCTTCACCGGCGCAGTTGTTCTTATAATTGCCCACGGACTTACATCAT... Pongo AAGCTTCACCGGCGCAACCACCCTCATGATTGCCCATGGACTCACATCCT... AAGCTTTACAGGTGCAACCGTCCTCATAATCGCCCACGGACTAACCTCTT... Hylobates Macaco Fuscata AAGCTTTTCCGGCGCAACCATCCTTATGATCGCTCACGGACTCACCTCTT...



Tarsius Lemur Homo Sapiens Chimp Gorilla Pongo Hylobates Macaco Fuscata

#### DISTANCE MATRIX



/	0.00	0.29	0.40	0.39	0.38	0.34	0.38	0.37
1	0.29	0.00	0.37	0.38	0.35	0.33	0.36	0.34
	0.40	0.37	0.00	0.10	0.11	0.15	0.21	0.24
	0.39	0.38	0.10	0.00	0.12	0.17	0.21	0.24
	0.38	0.35	0.11	0.12	0.00	0.16	0.21	0.26
	0.34	0.33	0.15	0.17	0.16	0.00	0.22	0.24
	0.38	0.36	0.21	0.21	0.21	0.22	0.00	0.26
/	0.37	0.34	0.24	0.24	0.26	0.24	0.26	0.00

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- **SECOND SECOND S**
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### WHAT IS AN OPTIMIZATION PROBLEM?

#### TWO INGREDIENTS

- A search space S (possibly constrained)
- ② A function  $f: S \to \mathbb{R}$  to optimize: find  $\bar{x}$  such that  $f(\bar{x}) = \max_{x \in S} f(x)$ .
  - If S is discrete (integers, graphs, trees), then we talk of combinatorial optimization.
  - If S is continuous ( $\mathbb{R}$ ), then we talk of continuous optimization.

#### BAD NEWS... (OR GOOD ONES?)

"Interesting" combinatorial optimization problems are usually  $\mathcal{NP}$ -hard.

#### THE SPACE OF TREES

The search space is the space of trees, usually with branch lengths. Branch lengths can be optimized for a given tree topology in an easy way. The bottleneck is the identification of the correct tree topology!

#### TREE TOPOLOGIES

- Rooted vz Unrooted
- Labeled vz Unlabeled (leaves)
- Bifurcating vz Multifurcating

### HOW MANY TOPOLOGIES ARE THERE?

We count the rooted labeled bifurcating trees.

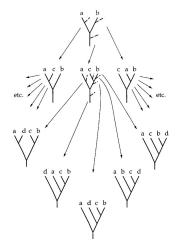
#### KEY PROPERTY

Each tree with n tips (leaves) can be obtained in a unique way from a tree with k leaves adding in sequence the remaining n-k leaves.

In fact, reversing the sequence and removing the n-k leaves, one obtains a unique tree with k leaves.

#### HOW MANY TOPOLOGIES ARE THERE?

We count the rooted labeled bifurcating trees.



#### TREES WITH *n* LEAVES

$$NT_{r,l,b}(n) = 3 \cdot 5 \cdots (2n-3) = \frac{(2n-3)!}{2^{n-2}(n-2)!}$$

### HOW MANY TOPOLOGIES ARE THERE?

We count the rooted labeled bifurcating trees.

Species	Number of Trees
3	3
4	15
5	105
6	945
7	10.395
8	135.135
9	2.027.025
10	34.459.425
15	213.458.046.676.875
20	8.200.794.532.637.891.559.375
30	$4,9518 \times 10^{38}$
40	$1,00985 \times 10^{57}$
50	$2.75292 \times 10^{76}$

#### TREES WITH *n* LEAVES

$$NT_{r,l,b}(n) = \frac{(2n-3)!}{2^{n-2}(n-2)!}$$

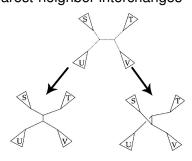
#### SEARCHING THE TREE SPACE: HEURISTIC METHODS

- The  $\mathcal{NP}$ -hardness of optimization problems on the tree space calls for heuristic solutions.
- Heuristic optimization algorithms usually search the space by following a trajectory that hopefully will hit good solutions, even the optimal one (trajectory-based heuristics).
- The next point of the trajectory is chosen in the neighbor of the current one.

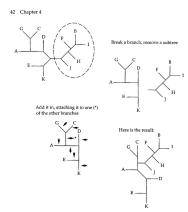
#### NEIGHBORHOODS FOR THE TREE SPACE

- Nearest-neighbor interchanges
- Subtree pruning and regrafting

# Nearest-neighbor interchanges

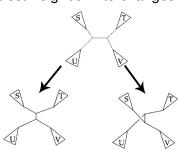


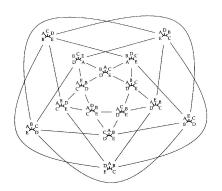
### Subtree pruning and regrafting



### NEIGHBORHOODS FOR THE TREE SPACE

### Nearest-neighbor interchanges

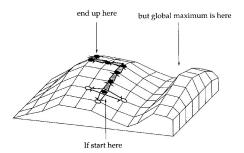




### HEURISTIC ALGORITHMS

#### TRAJECTORY METHODS

- Local Optimization
- Greedy Search
- Simulated Annealing
- GRASP
- Taboo Search



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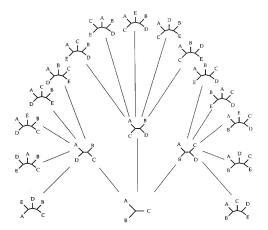
#### POPULATION METHODS

- Genetic Algorithms
- Ant Colony Optimization
- Particle swarm optimization

## Branch and Bound is a technique that explores a portion of the search space that is guaranteed to contain the optimal solution. It is an intelligent exhaustive search.

- Trees are constructed incrementally, adding one species at time. If the current tree is known to lead to a worse solution to the best one found so far, the algorithm backtracks and reconsider previous choices.
- The algorithm needs to estimate upper and lower bounds on the function to be optimized from partial solutions.
- It worst complexity is exponential, but it works well in practice.

### BRANCH AND BOUND - SEARCH TREE



Branch and Bound can be seen as a visit of a search tree, pruning some subtrees (according to bounds) and backtracking before reaching leaves.

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# LEAST SQUARE METHOD

We have our observed distance matrix  $D_{ii}$  and a tree T with branch lengths predicting an additive distance matrix  $d_{ii}$ .

#### TARGET

Find the tree T minimizing the error between  $d_{ii}$  and  $D_{ii}$ , i.e. the tree minimizing the weighted least square sum

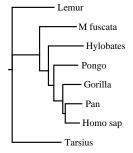
LEAST SOUARE METHODS

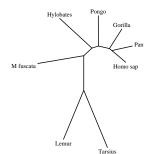
$$S(T) = \sum_{i,j} w_{ij} (D_{ij} - d_{ij})^2$$

- Given a tree topology, the best branch lengths for S can be computed by solving a linear system.
- A least square algorithms needs to search the tree space for the best tree T: this is an  $\mathcal{NP}$ -hard problem.
- The search for the best tree can use branch and bound methods or heuristic state space explorations.
- This method gives the best explanation of the data

### FITCH-MARGOLIAS ALGORITHM

- Letting  $w_{ij} = \frac{1}{D_{ij}^2}$  in  $S(T) = \sum_{i,j} w_{ij} (D_{ij} d_{ij})^2$ , we obtain the method of Fitch-Margoliash.
- The choice of  $\frac{1}{D_{ij}^2}$  has statistical reasons: it takes into account the variance from the expected additive distances.





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### HEURISTIC METHODS: UPGMA

#### HIERARCHICAL CLUSTERING

- Hierarchical clustering works by iteratively merging the two closest clusters (sets of elements) in the current collection of clusters.
- It requires a matrix of distances among singletons.
- Different ways of computing intercluster distances give rise to different HC-algorithms.

#### **UPGMA**

- UPGMA (Unweighted Pair Group Method with Arithmetic mean) computes the distance between two clusters as  $d(A, B) = \frac{1}{|A||B|} \sum_{i \in A, j \in B} d_{ij}$ .
- When two clusters A and B are merged, their union is represented by their ancestor node in the tree.
- The distance between A and B is evenly split between the two branches entering in A and B

# UPGMA - AN EXAMPLE

	Α	В	С	D	Ε
В	2				
С	4	4			
D	6	6	6		
Ε	6	6	6	4	
F	8	8	8	8	8

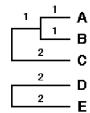
$$d([A,B],C) = \frac{1}{2}(d(A,C) + d(B,C)) = 4$$

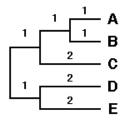
		A, B	C	D	E	
•	С	4				
	D	6	6			
	Ε	6	6	4		
	F	8	8	8	8	

# UPGMA - AN EXAMPLE

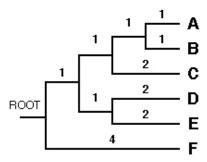
	A, B	C	D, E
C	4		
D, E	6	6	
F	8	8	8

	A, B, C	D, E
D, E	6	
F	8	8

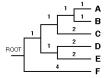




# UPGMA - AN EXAMPLE

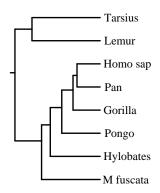


### **UPGMA** - CONSIDERATIONS



### HYPOTHESIS

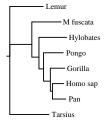
UPGMA reconstructs correctly the tree if the input distance is an ultrametric (molecular clock).

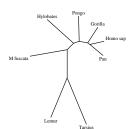


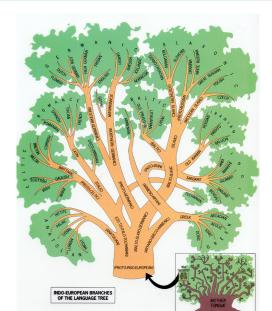
### HEURISTIC METHODS: NEIGHBOR-JOINING

#### **NEIGHBOR-JOINING**

- Neighbor-Joining works similarly to UPGMA, but it merges together the two clusters minimizing  $D_{ij} = d_{ij} r_i r_j$ , where  $r_i = \frac{1}{C-2} \sum_k d_{ik}$  is the average distance of i from all other nodes.
- When *i* and *j* are merged, their new ancestor *x* has distances from another node *k* equal to  $d_{xk} = \frac{1}{2}(d_{ik} + d_{jk} d_{ij})$
- The branch lengths are  $d_{ix} = \frac{1}{2}(d_{ij} + r_i r_j)$  and  $d_{jx} = \frac{1}{2}(d_{ij} + r_j r_i)$ .
- NJ reconstructs the correct tree if the input distance is additive.







### THE END

# Thanks for the attention!

